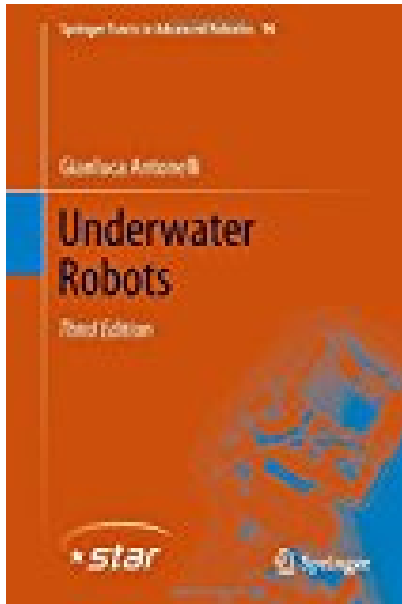


Underwater Robots Springer Tracts in Advanced Robotics



BOOK DETAILS

- Author : Gianluca Antonelli
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- Publisher : Springer
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BOOK SYNOPSIS

This book deals with the state of the art in underwater robotics experiments of dynamic control of an underwater vehicle. The author presents experimental results on motion control and fault tolerance to thrusters' faults with the autonomous vehicle ODIN. This second substantially improved and expanded edition new features are presented dealing with fault-tolerant control and coordinated control of autonomous underwater vehicles.

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